

# NAG Toolbox for MATLAB

## f08wb

### 1 Purpose

f08wb computes for a pair of  $n$  by  $n$  real nonsymmetric matrices  $(A, B)$  the generalized eigenvalues and, optionally, the left and/or right generalized eigenvectors using the *QZ* algorithm.

Optionally it also computes a balancing transformation to improve the conditioning of the eigenvalues and eigenvectors, reciprocal condition numbers for the eigenvalues, and reciprocal condition numbers for the right eigenvectors.

### 2 Syntax

```
[a, b, alphas, alphas_i, betas, vl, vr, ilo, ihi, lscales, rscales, abnorms,
bbnorms, rcondes, rcondv, info] = f08wb(balanc, jobvl, jobvr, sense, a, b,
'n', n)
```

### 3 Description

A generalized eigenvalue for a pair of matrices  $(A, B)$  is a scalar  $\lambda$  or a ratio  $\alpha/\beta = \lambda$ , such that  $A - \lambda B$  is singular. It is usually represented as the pair  $(\alpha, \beta)$ , as there is a reasonable interpretation for  $\beta = 0$ , and even for both being zero.

The right eigenvector  $v_j$  corresponding to the eigenvalue  $\lambda_j$  of  $(A, B)$  satisfies

$$Av_j = \lambda_j Bv_j.$$

The left eigenvector  $u_j$  corresponding to the eigenvalue  $\lambda_j$  of  $(A, B)$  satisfies

$$u_j^H A = \lambda_j u_j^H B.$$

where  $u_j^H$  is the conjugate-transpose of  $u_j$ .

All the eigenvalues and, if required, all the eigenvectors of the generalized eigenproblem  $Ax = \lambda Bx$ , where  $A$  and  $B$  are real, square matrices, are determined using the *QZ* algorithm. The *QZ* algorithm consists of four stages:

- (i)  $A$  is reduced to upper Hessenberg form and at the same time  $B$  is reduced to upper triangular form.
- (ii)  $A$  is further reduced to quasi-triangular form while the triangular form of  $B$  is maintained. This is the real generalized Schur form of the pair  $(A, B)$ .
- (iii) The quasi-triangular form of  $A$  is reduced to triangular form and the eigenvalues extracted. This function does not actually produce the eigenvalues  $\lambda_j$ , but instead returns  $\alpha_j$  and  $\beta_j$  such that

$$\lambda_j = \alpha_j / \beta_j, \quad j = 1, 2, \dots, n.$$

The division by  $\beta_j$  becomes your responsibility, since  $\beta_j$  may be zero, indicating an infinite eigenvalue. Pairs of complex eigenvalues occur with  $\alpha_j / \beta_j$  and  $\alpha_{j+1} / \beta_{j+1}$  complex conjugates, even though  $\alpha_j$  and  $\alpha_{j+1}$  are not conjugate.

- (iv) If the eigenvectors are required they are obtained from the triangular matrices and then transformed back into the original co-ordinate system.

For details of the balancing option, see Section 3 of the document for f08wh.

### 4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

Wilkinson J H 1979 Kronecker's canonical form and the *QZ* algorithm *Linear Algebra Appl.* **28** 285–303

## 5 Parameters

### 5.1 Compulsory Input Parameters

1: **balanc** – string

Specifies the balance option to be performed.

**balanc** = 'N'

Do not diagonally scale or permute.

**balanc** = 'P'

Permute only.

**balanc** = 'S'

Scale only.

**balanc** = 'B'

Both permute and scale.

Computed reciprocal condition numbers will be for the matrices after permuting and/or balancing. Permuting does not change condition numbers (in exact arithmetic), but balancing does. In the absence of other information, **balanc** = 'B' is recommended.

*Constraint:* **balanc** = 'N', 'P', 'S' or 'B'.

2: **jobvl** – string

If **jobvl** = 'N', do not compute the left generalized eigenvectors.

If **jobvl** = 'V', compute the left generalized eigenvectors.

*Constraint:* **jobvl** = 'N' or 'V'.

3: **jobvr** – string

If **jobvr** = 'N', do not compute the right generalized eigenvectors.

If **jobvr** = 'V', compute the right generalized eigenvectors.

*Constraint:* **jobvr** = 'N' or 'V'.

4: **sense** – string

Determines which reciprocal condition numbers are computed.

**sense** = 'N'

None are computed.

**sense** = 'E'

Computed for eigenvalues only.

**sense** = 'V'

Computed for eigenvectors only.

**sense** = 'B'

Computed for eigenvalues and eigenvectors.

*Constraint:* **sense** = 'N', 'E', 'V' or 'B'.

5: **a(lda,\*) – double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The matrix  $A$  in the pair  $(A, B)$ .

6: **b(ldb,\*) – double array**

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

The matrix  $B$  in the pair  $(A, B)$ .

**5.2 Optional Input Parameters**1: **n – int32 scalar**

*Default:* The first dimension of the arrays **a**, **b** and the second dimension of the arrays **a**, **b**. (An error is raised if these dimensions are not equal.)

$n$ , the order of the matrices  $A$  and  $B$ .

*Constraint:*  $\mathbf{n} \geq 0$ .

**5.3 Input Parameters Omitted from the MATLAB Interface**

lda, ldb, ldvl, ldvr, work, lwork, iwork, bwork

**5.4 Output Parameters**1: **a(lda,\*) – double array**

The first dimension of the array **a** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

**a** has been overwritten. If **jobvl** = 'V' or **jobvr** = 'V' or both, then  $A$  contains the first part of the real Schur form of the 'balanced' versions of the input  $A$  and  $B$ .

2: **b(ldb,\*) – double array**

The first dimension of the array **b** must be at least  $\max(1, \mathbf{n})$

The second dimension of the array must be at least  $\max(1, \mathbf{n})$

**b** has been overwritten.

3: **alphar(\*) – double array**

**Note:** the dimension of the array **alphar** must be at least  $\max(1, \mathbf{n})$ .

The element **alphar**( $j$ ) contains the real part of  $\alpha_j$ .

4: **alphai(\*) – double array**

**Note:** the dimension of the array **alphai** must be at least  $\max(1, \mathbf{n})$ .

The element **alphai**( $j$ ) contains the imaginary part of  $\alpha_j$ .

5: **beta(\*) – double array**

**Note:** the dimension of the array **beta** must be at least  $\max(1, \mathbf{n})$ .

$(\mathbf{alphar}(j) + \mathbf{alphai}(j) \times i) / \mathbf{beta}(j)$ , for  $j = 1, \dots, \mathbf{n}$ , will be the generalized eigenvalues.

If  $\mathbf{alpha}(j)$  is zero, then the  $j$ th eigenvalue is real; if positive, then the  $j$ th and  $(j+1)$ st eigenvalues are a complex conjugate pair, with  $\mathbf{alpha}(j+1)$  negative.

**Note:** the quotients  $\mathbf{alpha}(j)/\mathbf{beta}(j)$  and  $\mathbf{alpha}(j)/\mathbf{beta}(j)$  may easily overflow or underflow, and  $\mathbf{beta}(j)$  may even be zero. Thus, you should avoid naively computing the ratio  $\alpha_j/\beta_j$ . However,  $\max|\alpha_j|$  will always be less than and usually comparable with  $\|\mathbf{a}\|_2$  in magnitude, and  $\max|\beta_j|$  will always be less than and usually comparable with  $\|\mathbf{b}\|_2$ .

6: **vl(ldvl,\*) – double array**

The first dimension, **ldvl**, of the array **vl** must satisfy

if **jobvl** = 'V',  $\mathbf{ldvl} \geq \max(1, \mathbf{n})$ ;  
**ldvl**  $\geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{n})$  if **jobvl** = 'V', and at least 1 otherwise

If **jobvl** = 'V', the left eigenvectors  $u_j$  are stored one after another in the columns of **vl**, in the same order as the corresponding eigenvalues.

If the  $j$ th eigenvalue is real, then  $u_j = \mathbf{vl}(:,j)$ , the  $j$ th column of **vl**.

If the  $j$ th and  $(j+1)$ th eigenvalues form a complex conjugate pair, then  $u_j = \mathbf{vl}(:,j) + i \times \mathbf{vl}(:,j+1)$  and  $u_{j+1} = \mathbf{vl}(:,j) - i \times \mathbf{vl}(:,j+1)$ . Each eigenvector will be scaled so the largest component has  $|\text{real part}| + |\text{imag. part}| = 1$ .

If **jobvl** = 'N', **vl** is not referenced.

7: **vr(ldvr,\*) – double array**

The first dimension, **ldvr**, of the array **vr** must satisfy

if **jobvr** = 'V',  $\mathbf{ldvr} \geq \max(1, \mathbf{n})$ ;  
**ldvr**  $\geq 1$  otherwise.

The second dimension of the array must be at least  $\max(1, \mathbf{n})$  if **jobvr** = 'V', and at least 1 otherwise

If **jobvr** = 'V', the right eigenvectors  $v_j$  are stored one after another in the columns of **vr**, in the same order as their eigenvalues.

If the  $j$ th eigenvalue is real, then  $v(j) = \mathbf{vr}(:,j)$ , the  $j$ th column of **VR**.

If the  $j$ th and  $(j+1)$ th eigenvalues form a complex conjugate pair, then  $v_j = \mathbf{vr}(:,j) + i \times \mathbf{vr}(:,j+1)$  and  $v_{j+1} = \mathbf{vr}(:,j) - i \times \mathbf{vr}(:,j+1)$ .

Each eigenvector will be scaled so the largest component has  $|\text{real part}| + |\text{imag. part}| = 1$ .

If **jobvr** = 'N', **vr** is not referenced.

8: **ilo – int32 scalar**

9: **ihi – int32 scalar**

**ilo** and **ihi** are integer values such that  $\mathbf{a}(i,j) = 0$  and  $\mathbf{b}(i,j) = 0$  if  $i > j$  and  $j = 1, \dots, \mathbf{ilo} - 1$  or  $i = \mathbf{ihi} + 1, \dots, \mathbf{n}$ .

If **balanc** = 'N' or 'S', **ilo** = 1 and **ihi** = **n**.

10: **lscale(\*) – double array**

**Note:** the dimension of the array **lscale** must be at least  $\max(1, \mathbf{n})$ .

Details of the permutations and scaling factors applied to the left side of  $A$  and  $B$ .

If  $pl_j$  is the index of the row interchanged with row  $j$ , and  $dl_j$  is the scaling factor applied to row  $j$ , then:

**lscale**( $j$ ) =  $pl_j$ , for  $j = 1, \dots, \mathbf{ilo} - 1$ ;

**lscale** =  $dl_j$ , for  $j = \mathbf{ilo}, \dots, \mathbf{ihi}$ ;

**lscale** =  $pl_j$ , for  $j = \mathbf{ihi} + 1, \dots, \mathbf{n}$ .

The order in which the interchanges are made is  $\mathbf{n}$  to  $\mathbf{ihi} + 1$ , then 1 to  $\mathbf{ilo} - 1$ .

11: **rscale**(\*) – double array

**Note:** the dimension of the array **rscale** must be at least  $\max(1, \mathbf{n})$ .

Details of the permutations and scaling factors applied to the right side of  $A$  and  $B$ .

If  $pr_j$  is the index of the column interchanged with column  $j$ , and  $dr_j$  is the scaling factor applied to column  $j$ , then:

**rscale**( $j$ ) =  $pr_j$ , for  $j = 1, \dots, \mathbf{ilo} - 1$ ;

if **rscale** =  $dr_j$ , for  $j = \mathbf{ilo}, \dots, \mathbf{ihi}$ ;

if **rscale** =  $pr_j$ , for  $j = \mathbf{ihi} + 1, \dots, \mathbf{n}$ .

The order in which the interchanges are made is  $\mathbf{n}$  to  $\mathbf{ihi} + 1$ , then 1 to  $\mathbf{ilo} - 1$ .

12: **abnrm** – double scalar

The 1-norm of the balanced matrix  $A$ .

13: **bbnrm** – double scalar

The 1-norm of the balanced matrix  $B$ .

14: **rconde**(\*) – double array

**Note:** the dimension of the array **rconde** must be at least  $\max(1, \mathbf{n})$ .

If **sense** = 'E' or 'B', the reciprocal condition numbers of the eigenvalues, stored in consecutive elements of the array. For a complex conjugate pair of eigenvalues two consecutive elements of **rconde** are set to the same value. Thus **rconde**( $j$ ), **rcondv**( $j$ ), and the  $j$ th columns of **vl** and **vr** all correspond to the  $j$ th eigenpair.

If **sense** = 'V', **rconde** is not referenced.

15: **rcondv**(\*) – double array

**Note:** the dimension of the array **rcondv** must be at least  $\max(1, \mathbf{n})$ .

If **sense** = 'V' or 'B', the estimated reciprocal condition numbers of the eigenvectors, stored in consecutive elements of the array. For a complex eigenvector two consecutive elements of **rcondv** are set to the same value.

If **sense** = 'E', **rcondv** is not referenced.

16: **info** – int32 scalar

**info** = 0 unless the function detects an error (see Section 6).

## 6 Error Indicators and Warnings

Errors or warnings detected by the function:

**info** =  $-i$

If **info** =  $-i$ , parameter  $i$  had an illegal value on entry. The parameters are numbered as follows:

1: **balanc**, 2: **jobvl**, 3: **jobvr**, 4: **sense**, 5: **n**, 6: **a**, 7: **lda**, 8: **b**, 9: **ldb**, 10: **alphar**, 11: **alphai**, 12: **beta**, 13: **vl**, 14: **ldvl**, 15: **vr**, 16: **ldvr**, 17: **ilo**, 18: **ihi**, 19: **lscale**, 20: **rscale**, 21: **abnrm**, 22: **bbnrm**, 23: **rconde**, 24: **rcondv**, 25: **work**, 26: **lwork**, 27: **iwork**, 28: **bwork**, 29: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

**info** = 1 to  $N$

The  $QZ$  iteration failed. No eigenvectors have been calculated, but **alphar**( $j$ ), **alphai**( $j$ ), and **beta**( $j$ ) should be correct for  $j = \mathbf{info} + 1, \dots, n$ .

**info** =  $N + 1$

Unexpected error returned from f08xe.

**info** =  $N + 2$

Error returned from f08yk.

## 7 Accuracy

The computed eigenvalues and eigenvectors are exact for a nearby matrices  $(A + E)$  and  $(B + F)$ , where

$$\|(E, F)\|_F = O(\epsilon)\|(A, B)\|_F,$$

and  $\epsilon$  is the *machine precision*.

An approximate error bound on the chordal distance between the  $i$ th computed generalized eigenvalue  $w$  and the corresponding exact eigenvalue  $\lambda$  is

$$\epsilon \times \|\mathbf{abnrm}, \mathbf{bbnrm}\|_2 / \mathbf{rconde}(i).$$

An approximate error bound for the angle between the  $i$ th computed eigenvector **vl**( $i$ ) or **vr**( $i$ ) is given by

$$\epsilon \times \|\mathbf{abnrm}, \mathbf{bbnrm}\|_2 / \mathbf{rcondv}(i).$$

For further explanation of the reciprocal condition numbers **rconde** and **rcondv**, see Section 4.11 of Anderson *et al.* 1999.

**Note:** interpretation of results obtained with the  $QZ$  algorithm often requires a clear understanding of the effects of small changes in the original data. These effects are reviewed in Wilkinson 1979, in relation to the significance of small values of  $\alpha_j$  and  $\beta_j$ . It should be noted that if  $\alpha_j$  and  $\beta_j$  are **both** small for any  $j$ , it may be that no reliance can be placed on **any** of the computed eigenvalues  $\lambda_i = \alpha_i / \beta_i$ . You are recommended to study Wilkinson 1979 and, if in difficulty, to seek expert advice on determining the sensitivity of the eigenvalues to perturbations in the data.

## 8 Further Comments

The total number of floating-point operations is proportional to  $n^3$ .

The complex analogue of this function is f08wp.

## 9 Example

```
balanc = 'Balance';
jobvl = 'No vectors (left)';
jobvr = 'Vectors (right)';
sense = 'Both reciprocal condition numbers';
a = [3.9, 12.5, -34.5, -0.5;
     4.3, 21.5, -47.5, 7.5;
     4.3, 21.5, -43.5, 3.5;
     4.4, 26, -46, 6];
b = [1, 2, -3, 1;
     1, 3, -5, 4;
     1, 3, -4, 3;
     1, 3, -4, 4];
```

```
[aOut, bOut, alphas, alphai, beta, vl, vr, ilo, ihi, lscale, rscale, ...
  abnrm, bbnrm, rconde, rcondv, info] = ...
  f08wb(balanc, jobvl, jobvr, sense, a, b)
```

```
aOut =
    3.2224   -9.6500    6.6759    9.2824
         0    0.2275    0.7369    4.4114
         0   -0.2267    0.2253    2.4373
         0         0         0    2.8425

bOut =
    1.6112   -1.0652    0.7761    6.1473
         0    0.1849         0    1.8929
         0         0    0.0472    0.8504
         0         0         0    0.7106

alphas =
    3.2224
    0.3880
    0.2026
    2.8425

alphai =
         0
    0.5173
   -0.2701
         0

beta =
    1.6112
    0.1293
    0.0675
    0.7106

vl =
         0

vr =
   -1.0000   -0.4255   -0.5745   -1.0000
   -0.0057   -0.0851   -0.1149   -0.0111
   -0.0629   -0.1430   -0.0009    0.0333
   -0.0629   -0.1430   -0.0009   -0.1556

ilo =
         1

ihi =
         4

lscale =
         1
         1
         1
         1

rscale =
    1.0000
    0.1000
    0.1000
    1.0000

abnrm =
    17.5000

bbnrm =
    12

rconde =
    0.0952
    0.1652
    0.1652
    0.5141

rcondv =
    0.1254
    0.0381
    0.0381
    0.0707

info =
         0
```